

# Classical Mechanics

## Damped oscillator

**Problem 1.-** Prove that for a lightly damped oscillator, the change in frequency caused by the damping is approximately  $\frac{\omega_o}{8Q^2}$ . Based on that, if damping causes a 1% decrease in the frequency of an oscillator, what is its Q value?

**Solution:**

a) **Proof:**

When the system is lightly damped, the angular frequency drops to the value given by:

$$\omega_1 = \sqrt{\omega_o^2 - \beta^2}$$

We can rearrange the equation as follows:  $\omega_1 = \omega_o \sqrt{1 - \frac{\beta^2}{\omega_o^2}}$

If the system is truly lightly damped, the ratio  $\frac{\beta^2}{\omega_o^2}$  is small, so we can approximate the radical

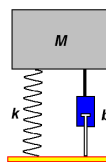
by:  $\omega_1 = \omega_o \left(1 - \frac{\beta^2}{2\omega_o^2}\right)$  so the change in frequency is  $\omega_o - \omega_1 = \omega_o \left(\frac{\beta^2}{2\omega_o^2}\right)$

But by definition  $Q = \frac{\omega_R}{2\beta} \approx \frac{\omega_o}{2\beta} \rightarrow \beta \approx \frac{\omega_o}{2Q}$

With this change of variable, we get:  $\omega_o - \omega_1 = \omega_o \left(\frac{\left(\frac{\omega_o}{2Q}\right)^2}{2\omega_o^2}\right) = \frac{\omega_o}{8Q^2}$

b) **1% decrease in the frequency:** It means that  $\frac{1}{8Q^2} = 0.01$ , so  $Q = \sqrt{\frac{1}{0.08}} = 3.5$

**Problem 2.-** Calculate the position  $x(t)$  of the critically damped oscillator shown in the figure whose mass is  $M=10\text{kg}$  and its spring constant  $k=40\text{N/m}$ . Consider that  $x$  is measured with respect to the equilibrium condition and the initial velocity  $v(0)=0$  and initial position  $x(0)=1.5\text{ m}$



**Solution:** The differential equation is:  $\ddot{x} + 2\beta\dot{x} + \omega_o^2 = 0$

If the oscillator is critically damped, it means that:  $\beta = \omega_o = \sqrt{\frac{k}{m}} = \sqrt{\frac{20}{5}} = 2 \text{ rad / s}$

The solution has the form:  $x = Ae^{-2t} + Bte^{-2t}$

The initial conditions will give us the constants **A** and **B**:

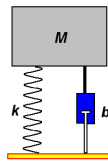
$$x(0) = 1.5 = A$$

and

$$\dot{x}(0) = -2Ae^{-2t} + Be^{-2t} - 2Bte^{-2t} = -2A + B - 2Bt = -2A + B = 0 \rightarrow B = 3$$

$$x = 1.5e^{-2t} + 3te^{-2t}$$

**Problem 2a.-** Calculate the position  $x(t)$  of the critically damped oscillator shown in the figure whose mass is  $M=5\text{kg}$  and its spring constant  $k=20\text{N/m}$ . Consider that  $x$  is measured with respect to the equilibrium condition and the initial velocity  $v(0)=0$  and initial position  $x(0)=1.5 \text{ m}$



**Solution:**

The differential equation is:  $\ddot{x} + 2\beta\dot{x} + \omega_o^2 = 0$

If the oscillator is critically damped, it means that:  $\beta = \omega_o = \sqrt{\frac{k}{m}} = \sqrt{\frac{20}{5}} = 2 \text{ rad / s}$

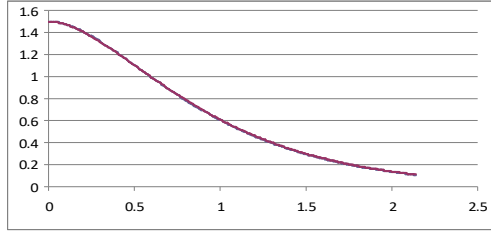
The solution has the form:  $x = Ae^{-2t} + Bte^{-2t}$

The initial conditions will give us the constants **A** and **B**:

$$x(0) = 1.5 = A$$

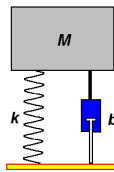
and  $\dot{x}(0) = -2Ae^{-2t} + Be^{-2t} - 2Bte^{-2t} = -2A + B - 2Bt = -2A + B = 0 \rightarrow B = 3$

$$x = 1.5e^{-2t} + 3te^{-2t}$$



**Problem 2c.-** Calculate the free response of the oscillator shown in the figure. Indicate  $x(t)$  as a function of time as your answer. Consider that  $x$  is measured with respect to the equilibrium condition and the initial velocity  $v=6\text{m/s}$  and initial position  $x=0$

$M=5\text{kg}$ ,  $k=5\text{ N/m}$  and  $b=1\text{ Ns/m}$



**Solution:**  $\ddot{x} + 2\beta\dot{x} + \omega_0^2 = 0$

$$\beta = \frac{b}{2M} = \frac{1}{2 \times 5} = 0.1$$

$$\omega_1 = \sqrt{\omega_0^2 - \beta^2} = \sqrt{1 - 0.1^2} = 0.995 \dots \text{ Under-damped case.}$$

$$x = Ae^{-0.1t} \sin(0.995t) + Be^{-0.1t} \cos(0.995t)$$

Initial conditions:

$$x(0) = B = 0 \rightarrow B = 0$$

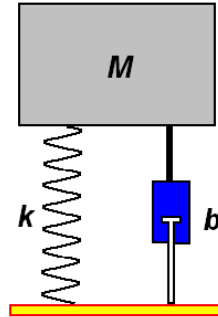
$$\dot{x}(t) = -0.1Ae^{-0.1t} \sin(0.995t) + Ae^{-0.1t} \cos(0.995t)$$

$$\dot{x}(0) = A \cdot 0.995 = 6 \rightarrow A = 6.03$$

$$\text{Solution: } x = 6.03e^{-0.1t} \sin(0.995t)$$

**Problem 2d.-** Calculate the free response of the oscillator shown in the figure. Indicate  $x(t)$  as a function of time as your answer.

Consider that  $x$  is measured with respect to the equilibrium condition and the initial velocity  $v=0.5\text{m/s}$  and  $x(0)=1\text{m}$



- a) for  $M=2.5\text{kg}$ ,  $k=10\text{ N/m}$  and  $b=5\text{ Ns/m}$
- b) for  $M=2.5\text{kg}$ ,  $k=10\text{ N/m}$  and  $b=10\text{ Ns/m}$
- c) for  $M=2.5\text{kg}$ ,  $k=10\text{ N/m}$  and  $b=20\text{ Ns/m}$

**Solution:**

$$a) \ddot{x} + 2\beta\dot{x} + \omega_0^2 = 0$$

$$\beta = \frac{b}{2M} = \frac{5}{2 \times 2.5} = 1 \text{ rad/s}$$

$$\omega_1 = \sqrt{\omega_0^2 - \beta^2} = \sqrt{4 - 1^2} = 1.73 \text{ rad/s} \dots \text{ Under-damped case.}$$

$$x = Ae^{-t} \sin(1.73t) + Be^{-t} \cos(1.73t)$$

Initial conditions:

$$x(0) = B = 1 \rightarrow B = 1$$

$$\dot{x}(t) = -Ae^{-t} \sin(1.73t) - Be^{-t} \cos(1.73t) + 1.73Ae^{-t} \cos(1.73t) - 1.73Be^{-t} \sin(1.73t)$$

$$\dot{x}(0) = -B + 1.73A = 0.5 \rightarrow A = \frac{0.5 + 1}{1.73} = 0.866$$

$$\text{Solution: } x = 0.866e^{-t} \sin(1.73t) + e^{-t} \cos(1.73t)$$

$$b) \ddot{x} + 2\beta\dot{x} + \omega_0^2 = 0$$

$$\beta = \frac{b}{2M} = 2 \text{ rad/s}$$

$$\omega_1 = \sqrt{\omega_0^2 - \beta^2} = 0 \dots \text{ Critically damped case}$$

$$x = Ae^{-2t} + Bte^{-2t}$$

Initial conditions:

$$x(0) = A = 1$$

$$\dot{x}(t) = -2Ae^{-2t} - 2Bte^{-2t} + Be^{-2t}$$

$$\dot{x}(0) = -2A + B = 0.5 \rightarrow B = 2.5$$

$$\text{Solution: } x = e^{-2t} + 2.5te^{-2t}$$

$$c) \ddot{x} + 2\beta\dot{x} + \omega_o^2 = 0$$

$$\beta = \frac{b}{2M} = \frac{20}{2 \times 2.5} = 4 \text{ rad / s}$$

Over-damped case:

$$r_1 = -\beta + \sqrt{\beta^2 - \omega_o^2} = -4 + \sqrt{12} = -0.535$$

$$r_2 = -\beta - \sqrt{\beta^2 - \omega_o^2} = -4 - \sqrt{12} = -7.464$$

$$x = Ae^{-0.535t} + Be^{-7.464t}$$

Initial conditions:

$$x(0) = A + B = 1$$

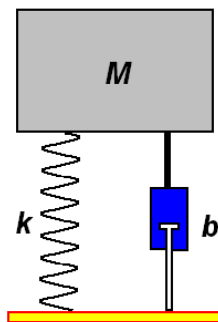
$$\dot{x}(0) = -0.535A - 7.464B = 0.5$$

$$\text{So: } A = \frac{\begin{vmatrix} 1 & 1 \\ 0.5 & -7.464 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ -0.535 & -7.464 \end{vmatrix}} = \frac{-7.464 - 0.5}{-7.464 + 0.535} = 1.15 \rightarrow B = -0.15$$

$$\text{Solution: } x = 1.15e^{-0.535t} - 0.15e^{-7.464t}$$

**Problem 2e.-** Calculate the free response of the oscillator shown in the figure. Indicate  $x(t)$  as a function of time as your answer.

Consider that  $x$  is measured with respect to the equilibrium condition and the initial velocity  $v=0.15\text{m/s}$  and  $x(0)=0$



- a) for  $M=2.5\text{kg}$ ,  $k=10\text{ N/m}$  and  $b=5\text{ Ns/m}$
- b) for  $M=2.5\text{kg}$ ,  $k=10\text{ N/m}$  and  $b=10\text{ Ns/m}$
- c) for  $M=2.5\text{kg}$ ,  $k=10\text{ N/m}$  and  $b=20\text{ Ns/m}$

**Solution:**

$$\text{a) } \ddot{x} + 2\beta\dot{x} + \omega_0^2 = 0$$

$$\beta = \frac{b}{2M} = \frac{5}{2 \times 2.5} = 1 \text{ rad/s}$$

$$\omega_1 = \sqrt{\omega_0^2 - \beta^2} = \sqrt{4 - 1} = 1.73 \text{ rad/s} \dots \text{ Under-damped case.}$$

$$x = Ae^{-t} \sin(1.73t + \phi)$$

Initial conditions:

$$x(0) = A \sin(\phi) = 0 \rightarrow \phi = 0$$

$$\dot{x}(0) = 1.73A \cos(0) = 0.15 \rightarrow A = \frac{0.15}{1.73}$$

$$\text{Solution: } x = 0.0866e^{-t} \sin(1.73t)$$

$$\text{b) } \ddot{x} + 2\beta\dot{x} + \omega_0^2 = 0$$

$$\beta = \frac{b}{2M} = 2 \text{ rad/s}$$

$$\omega_1 = \sqrt{\omega_0^2 - \beta^2} = 0 \dots \text{ Critically damped case}$$

$$x = Ae^{-2t} + Bte^{-2t}$$

Initial conditions:

$$x(0) = A = 0$$

$$\dot{x}(0) = B = 0.15$$

$$\text{Solution: } x = 0.15te^{-2t}$$

$$\text{c) } \ddot{x} + 2\beta\dot{x} + \omega_0^2 = 0$$

$$\beta = \frac{b}{2M} = \frac{20}{2 \times 2.5} = 4 \text{ rad/s}$$

Over-damped case:

$$r_1 = -\beta + \sqrt{\beta^2 - \omega_o^2} = -4 + \sqrt{12} = -0.535$$

$$r_2 = -\beta - \sqrt{\beta^2 - \omega_o^2} = -4 - \sqrt{12} = -7.464$$

$$x = Ae^{-0.535t} + Be^{-7.464t}$$

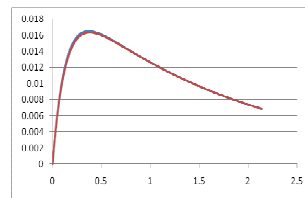
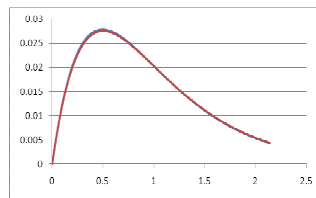
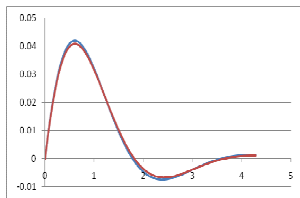
Initial conditions:

$$x(0) = A + B = 0$$

$$\dot{x}(0) = -0.535A - 7.464B = 0.15$$

$$\text{So: } A = \frac{\begin{vmatrix} 0 & 1 \\ 0.15 & -7.464 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ -0.535 & -7.464 \end{vmatrix}} = \frac{-0.15}{-7.464 + 0.535} = 0.0216 \text{ and } B = -0.0216$$

$$\text{Solution: } x = 0.0216(e^{-0.535t} - e^{-7.464t})$$



**Problem 3.-** A small fiber vibrates like a simple harmonic oscillator with light damping. In one experiment you determine that the maximum amplitude occurs when the driving frequency is  $f=134$  kHz, but the angular delay between driving force and oscillation reaches  $90^\circ$  at  $f=136$  kHz. Based on these results, what is the natural frequency of oscillation in the absence of damping and how much is  $\beta$ ?

**Solution:** The angular delay between driving force and oscillation is given by:

$$\delta = \tan^{-1}\left(\frac{2\beta\omega}{\omega_o^2 - \omega^2}\right)$$

This value reaches  $90^\circ$  when  $\omega_o = \omega$ , so  $\omega_o = 2\pi(136\text{kHz}) = 855$  krad/s

The resonance condition is  $\omega = \omega_R = \sqrt{\omega_o^2 - 2\beta^2}$ , so:

$$\beta = \sqrt{\frac{\omega_o^2 - \omega^2}{2}} = 2\pi\sqrt{\frac{136\text{kHz}^2 - 134\text{kHz}^2}{2}} = 104 \text{ krad/s}$$